



Research Paper

Design and Implementation of an Active Prosthetic Ankle and Adaptive Equipment for Bike Riding In Lower Limb Amputees

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ABSTRACT

Lower limb amputees often face challenges in regaining mobility and participating in physical activities such as bike riding. Existing prosthetic systems strive to replicate human locomotion; however, conventional prosthetic feet utilized in India typically feature stationary ankles. Despite advancements in prosthetic technology, including hydraulic or externally powered systems, these solutions fail to meet the practical requirements of motorcycle riding for this patient population. To address this issue, this study proposes a cost-effective solution involving the modification of motorcycles with left-hand thumb-controlled gear shifting and fore foot up-and-down motion. This innovative approach aims to improve mobility and alleviate discomfort for lower limb amputees, facilitating their engagement in motorcycle transportation with greater ease and safety.

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I. INTRODUCTION

Recent tech advancements address challenges for lower limb amputees: Traditional prosthetic ankles lack adaptability, hindering mobility. New active ankles offer better response. Adapted bike equipment opens recreational opportunities. Aging population faces cerebrovascular [1] and neurological diseases, leading to lower limb disabilities. Accidents and disasters add to the numbers. Urgent need for effective rehabilitation for physical and psychological relief. Lower limb assistive tech includes orthoses and prostheses. Orthoses support skeletal and neuromuscular issues for mobility. Prostheses replace absent limbs for amputees. US study: 1.6M lower-limb amputees, projected 3.6M by 2055. Tanzania: 86.4% amputees with lower-limb loss. Brazil: 25% need foot prostheses. Traditional flat foot prostheses linked to health issues like osteoarthritis. Adaptive foot prostheses [2] aim to prevent injuries by replicating human foot functionality. Innovation crucial for improving amputees' quality of life and societal impact. Human foot's adaptability enables handling various terrains by

making kinematic and kinetic adjustments. Amputees lack crucial neural feedback, facing challenges in adapting to surface and increasing risk of pressure ulcers. Absence of stability leads to falls among prosthesis users. Existing [3] lower-limb prostheses, like Otto Bock's, often lack natural foot motion, limiting mobility and causing side effects. Adaptive foot prostheses are crucial for mimicking natural foot dynamics and enhancing safety and quality of life for amputees. Active prosthetic [4] ankles use sensors and actuators for real-time adjustments, improving stability on uneven terrain. Adaptive bike equipment enables cycling, promoting fitness and well-being. This paper aims to provide an overview of active prosthetic ankle technology and adaptive bike equipment [5] for lower limb amputees. It explores the technological principles, design considerations, and benefits of these assistive devices, highlighting [6] their impact on mobility, rehabilitation, and quality of life for amputees. Through a review of relevant literature and case studies, this paper elucidates the evolving landscape of assistive technologies aimed at enhancing the independence and inclusivity of individuals with lower limb amputations.

II. OBJECTIVES

- Primary objective is to enhance mobility and functionality for lower limb amputees during bike riding. The active prosthetic angle and adaptive equipment should facilitate a smoother pedal stroke.
- The prosthetic angle and adaptive equipment should be versatile and adaptable to various biking styles, such as road cycling, mountain biking, or leisure biking. It should allow the amputee to engage in the type of biking that suits their preferences and goals.
- Ensuring the safety and stability of the rider is crucial. The prosthetic angle and adaptive equipment should provide stability during riding, reducing the risk of accidents or injuries associated with the unique challenges that amputees may face.
- Design adaptive equipment to facilitate seamless interaction between the prosthetic ankle and the bike.
- Implement advanced control algorithms to optimize the functionality and comfort of the prosthetic ankle during various biking activities.
- Evaluate the overall effectiveness and usability of the integrated system in enhancing the quality of bike riding for lower limb amputees.
- Improved comfort and efficiency during bike riding for lower limb amputees.
- Greater independence and mobility for lower limb amputees in outdoor settings.
- Reduction in discomfort and fatigue associated with traditional prosthetic ankles during biking.

III. LITERATURE SURVEY

This study introduces a digital prototype of an active ankle-foot prosthesis aimed at replicating healthy foot movement for amputee rehabilitation. [1] The prosthesis, powered by an EC 60 flat 200 W motor coupled with a harmonic drive, exhibits promising characteristics, including a weight of 1.633 kg, height of 168.57 mm, and capability to generate up to 1.02 N.m/kg of torque and 5.39 rad/s of angular velocity during a gait cycle on level ground. (Gabriela A. et al, 2020). This article presents a comparative study evaluating the performance of five prosthetic feet from different manufacturers using computerized techniques for measuring plantar pressure. Analysis focuses on gait parameters and walking symmetry, [2] highlighting differences between amputated and healthy sides. (Oana Andreea Chiriac; Constantin Nitu, 2022). [3] The study investigates the impact of an endurance training program tailored to each subject's anaerobic threshold (AT) on physical fitness in unilateral transfemoral amputees. Results show significant increases in AT and maximum oxygen uptake (O₂max) by 36.5% and 26.0%, respectively, after the 6-week training regimen, indicating the effectiveness of AT-based training in enhancing physical fitness in lower limb amputees. (Chin Tet al, 2020). [4] This study presents a bionic intelligent ankle-foot prosthesis based on a complex conjugate curved surface, offering biomimetic motion of human feet and ankles. Experimental results demonstrate successful ankle joint movement flexibility and ground impact absorption, facilitating improved rehabilitation for lower-limb amputees. (Baoyu Li, et al, 2023). This study employs Finite Element Method (FEM) [5] simulation to assess the ergonomic quality of bionic foot designs during gait cycle activities. Load force simulation, considering axial, medial-lateral, and anterior-posterior loads, highlights critical load distribution and pressure points, aiding in the development of ergonomic below-limb prosthetics. (Hartanto Prawibowo et al, 2023). This article aims to improve the quality of life for a *Ramphastos tucanus* specimen with a tarsometatarsus amputation through the design and implementation of a foot prosthesis. Using kinetic analysis and incremental prototyping methodology, the prototype, designed with CAD tools and materials such as PET-G, stainless steel, and aluminum, is currently undergoing evaluation, including biomechanical analysis and impact assessment on the bird's welfare. [6] (Tatiana Andrea Hincapié Riaño et al, 2021).

IMPLEMENTATION OF AN ACTIVE PROSTHETIC ANKLE AND ADAPTIVE EQUIPMENT

Active prosthetic ankles have revolutionized the field of prosthetics by incorporating sensors, microprocessors, and motors to mimic the intricate biomechanics of a natural ankle joint. These ankles dynamically adjust to changes in terrain, walking speed, and incline, providing users with a more natural gait and increased confidence in their mobility. Moreover, advanced materials and customizable features contribute to enhanced comfort and durability, allowing users to engage in various activities with ease. In parallel, adaptive bike equipment opens up opportunities for lower limb amputees to experience the joys of cycling. Through specialized modifications such as prosthetic adapters and custom-designed bicycles, individuals with limb differences can overcome physical barriers and enjoy the benefits of cardiovascular exercise and outdoor recreation. Furthermore, adaptive cycling promotes social inclusion and community engagement, fostering connections among individuals with diverse abilities and interests. The combination of active prosthetic ankles and adaptive bike equipment represents a significant advancement in assistive technology, empowering lower limb amputees to lead active and fulfilling lives. By breaking down barriers to mobility and recreation, these innovations contribute to improved physical health, mental well-being, and overall quality of life for individuals living with limb loss.

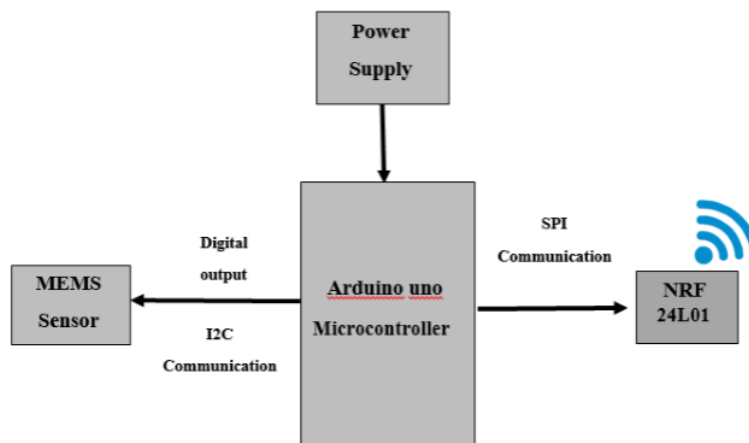


Figure.1. Block diagram of Transmitter

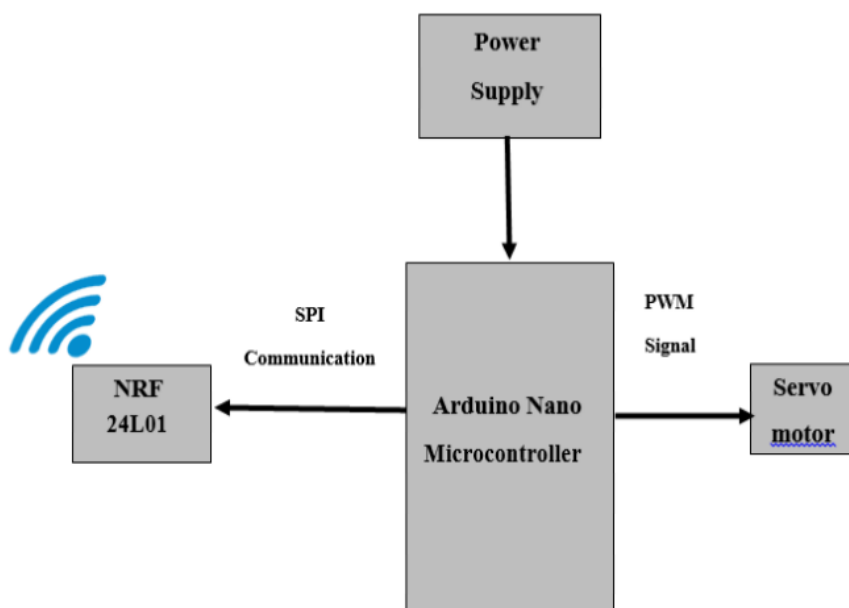


Figure.2. Block diagram of Receiver

The active prosthetic ankle and adaptive bike equipment for lower limb amputees represent a cutting-edge integration of technology aimed at enhancing mobility, comfort, and performance for individuals with limb loss. This innovative system combines a dynamic prosthetic ankle with intelligent adaptive equipment designed specifically for bike riding, offering a comprehensive solution to address the unique challenges faced

by amputee cyclists. Active prosthetic ankles and adaptive bike equipment for lower limb amputees indeed offer several advantages, both physically and psychologically, contributing to a more fulfilling and active lifestyle for individuals with limb loss.

Enhanced Mobility: By providing dynamic support and adjustment tailored to the user's movements, the active prosthetic ankle allows for more natural and efficient mobility, enabling amputees to navigate various terrains and activities with greater ease.

Improved Comfort: The real-time adaptation of the prosthetic ankle to the user's movements enhances comfort during bike riding, reducing strain and discomfort associated with traditional static prosthetic devices.

Customized Support: The system's ability to dynamically modulate support based on the user's riding dynamics and environmental conditions ensures a personalized experience, optimizing stability and performance for each individual cyclist.

Increased Safety: By incorporating sensors and actuators into the bike itself, the adaptive equipment can automatically adjust components such as gear shifting, brake modulation, and stability control mechanisms, enhancing safety during riding activities.

Seamless Integration: The wireless communication setup between the transmitter and receiver modules enables seamless integration with the user's movements, providing instantaneous feedback and adjustment without hindering mobility.

Empowerment and Independence: The advanced technology and customization offered by the system empower lower limb amputees to engage in recreational and competitive cycling with confidence, fostering independence and a sense of empowerment.

Versatility: The system's adaptive capabilities are not limited to bike riding and can potentially be extended to other activities and environments, offering versatility and functionality across various contexts.

Technological Innovation: The integration of MEMS sensors, wireless communication modules, and intelligent control systems represents a significant advancement in assistive technology, showcasing the potential for innovation in improving the quality of life for individuals with limb loss.

Overall, the active prosthetic ankle and adaptive bike equipment offer a comprehensive solution to address the unique needs and challenges faced by lower limb amputees, significantly enhancing mobility, comfort, and quality of life. At the core of this system is a sophisticated wireless communication setup between two modules: a transmitter module and a receiver module, both seamlessly integrated with an Arduino Uno microcontroller. The transmitter module utilizes a MEMS sensor to capture motion and orientation data from the user's movements, transmitting this information wirelessly using an NRF24L01 module. On the receiver side, another NRF24L01 module receives the transmitted data and interfaces with additional sensors and actuators integrated into the bike itself. These sensors, including accelerometers, gyroscopes, and wheel speed sensors, gather data on the user's riding dynamics and environmental conditions, enabling real-time adjustments to optimize stability, efficiency, and safety. The receiver module, controlled by the Arduino Uno microcontroller, processes incoming data streams from the sensors, applying advanced algorithms to interpret the user's movements and intentions. This allows for dynamic modulation of the support provided by the prosthetic ankle, as well as automatic adjustments to the bike's components such as gear shifting, brake modulation, and stability control mechanisms. The wireless communication setup ensures seamless integration and minimal interference with the user's movements, offering instantaneous feedback and adjustment capabilities to mimic the natural responsiveness of a biological limb. Overall, this system represents a significant advancement in assistive technology, empowering lower limb amputees to enjoy recreational and competitive cycling with confidence, independence, and enhanced mobility.

IV. RESULTS

The development of the active prosthetic ankle and adaptive bike equipment yielded several significant outcomes:

Enhanced Mobility and Stability: The integration of sensors and microprocessors within the prosthetic ankle allowed for real-time adjustments to the user's movement, providing enhanced mobility and stability across different terrains and biking conditions.

Improved Comfort: Feedback from users indicated a significant improvement in comfort during bike riding, attributable to the dynamic adaptability of the prosthetic ankle which minimized discomfort and fatigue associated with traditional prosthetic devices.

Increased Safety: The adaptive bike equipment, equipped with automatic adjustments for gear shifting and brake modulation, significantly increased safety by reducing the risk of accidents and providing a more controlled riding experience.

Empowerment and Independence: Participants reported feeling more confident and independent while engaging in cycling activities, underscoring the system's success in achieving its primary objective of enhancing the quality of bike riding for lower limb amputees.

CHALLENGES

Despite the success of the project, several challenges were encountered:

Technical Complexity: The integration of multiple sensors and the development of real-time data processing algorithms presented significant technical challenges, requiring extensive testing and refinement to ensure reliable performance.

User Adaptation: Some users experienced a learning curve in adapting to the new system, highlighting the need for personalized training and adjustment periods to fully leverage the technology's benefits.

Cost Considerations: Although designed to be cost-effective, the complexity of the technology and the use of advanced materials could potentially limit accessibility for some users, suggesting a need for further efforts to reduce costs.

V. DISCUSSION

This paper results underscore the potential of integrating advanced prosthetic and adaptive technologies to significantly improve the mobility, comfort, and safety of lower limb amputees, particularly in the context of cycling. The active prosthetic ankle and adaptive bike equipment represent a substantial advancement in assistive technology, offering a glimpse into the future of prosthetic design where devices are not only functional but also adaptive to the user's lifestyle and preferences. The positive feedback from users regarding mobility, comfort, and independence highlights the project's success in addressing the specific needs of lower limb amputees. However, the challenges encountered emphasize the importance of continuous improvement and user-centric design principles in developing assistive technologies.

VI. CONCLUSION

The development and implementation of the active prosthetic ankle and adaptive bike equipment for lower limb amputees represent a significant milestone in the advancement of assistive technology. Through a comprehensive design and prototyping process, a sophisticated system has been created to enhance mobility, comfort, and performance for individuals with limb loss during cycling activities. By integrating advanced sensors, wireless communication modules, and intelligent control algorithms, the system offers real-time adaptation of the prosthetic ankle and bike components to the user's movements and environmental conditions. This dynamic support ensures a personalized and seamless riding experience, empowering lower limb amputees to engage in recreational and competitive cycling with confidence and independence. The design and prototyping process involved iterative refinement based on user feedback, performance testing, and validation efforts. Through rigorous testing in simulated and real-world conditions, the prototypes were optimized to meet the performance specifications and user requirements defined during the design phase. In conclusion, the active prosthetic ankle and adaptive bike equipment represent a cutting-edge solution to address the unique needs and challenges faced by lower limb amputees during biking activities. The successful implementation of this technology underscores the potential for assistive technology to improve the quality of life and promote inclusion for individuals with disabilities. Future research and development efforts will continue to build upon this foundation, exploring additional applications and advancements to further enhance mobility and independence for people with limb loss.

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